

**An Extreme-Adaptive Time Series Prediction Model Based on
Probability-Enhanced LSTM Neural Networks**

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Problem: Univariate Time Series with Extreme Events Forecasting

$$[X_1, X_2, \dots, X_T] \in R^T \rightarrow [X_{T+1}, \dots, X_{T+H}], \in R^H$$

Challenges:

- Most values are normal and contribute significantly to the overall prediction performance
- Few extreme values but they must be precisely forecasted to avoid disastrous events

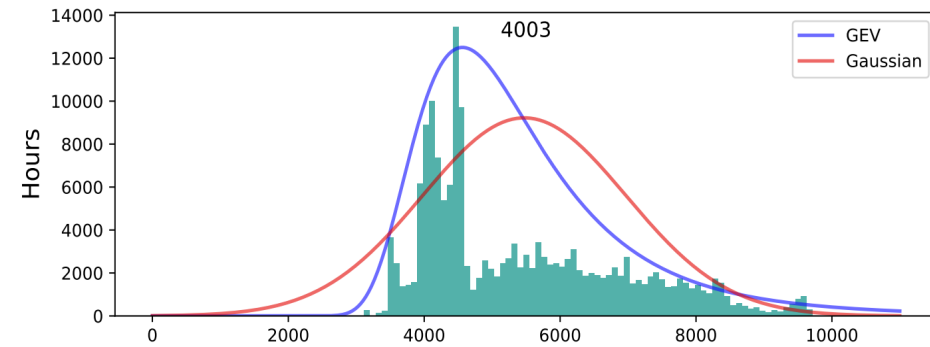
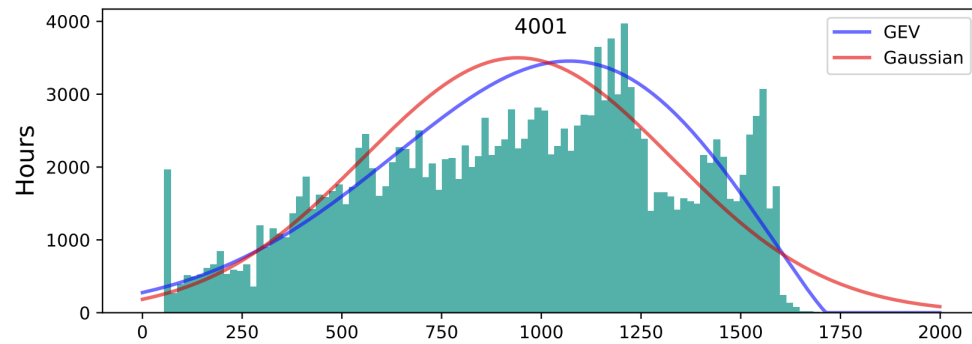
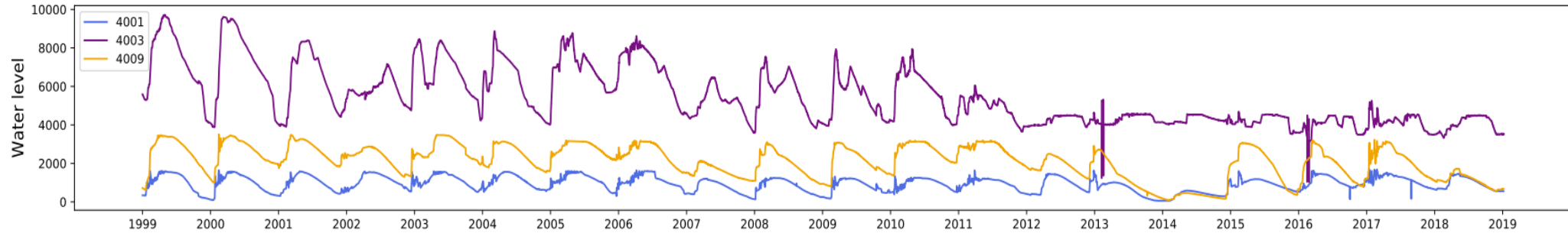
Goal:

- A model that concurrently learns extreme and normal prediction functions
- Long sequence forecasting
- Good generalization

Dataset:

- We evaluate the proposed model on the difficult 3-day ahead hourly water level prediction task applied to 9 reservoirs in California

Extreme Events:



GEV (Generalized Extreme Value) distribution provides a better fit, showing the presence of extreme values in our data,

$$F(x; \mu, \sigma, \xi) = \exp \left\{ - \left[1 + \xi \left(\frac{x - \mu}{\sigma} \right) \right]^{-1/\xi} \right\}, \quad (1)$$

where $\mu \in \mathbb{R}$, $\sigma > 0$, and ξ are the location, scale, and shape parameters, respectively, conditioned on $1 + \xi(x - \mu)/\sigma > 0$.

Motivation: achieving the best overall prediction performance, without sacrificing either the quality of normal or of extreme predictions.

Root Mean Square Error (*RMSE*)

Mean Absolute Percentage Error (*MAPE*)

Proposed Methods:

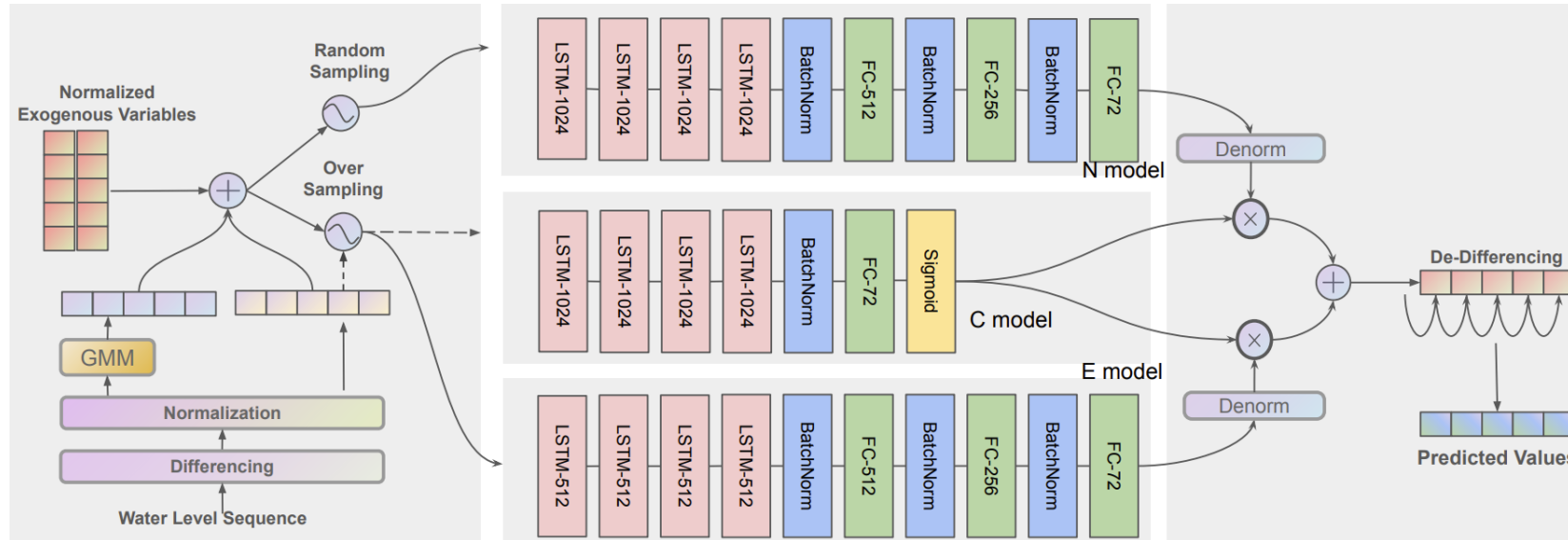
NEC framework: a framework to account for the distribution shift between normal and extreme values; composed of a *Normal*, an *Extreme*, and a *Classification* model.

GMM Indicator: an unsupervised clustering approach to dynamically produce distribution indicators, which improves the model's robustness to the occurrence of severe events.

Selected Backpropagation: helps the models learn the positions and values of appropriate normal or extreme data better.

Parameterized Loss Function: helps our classifier better distinguish event severity.

NEC framework :

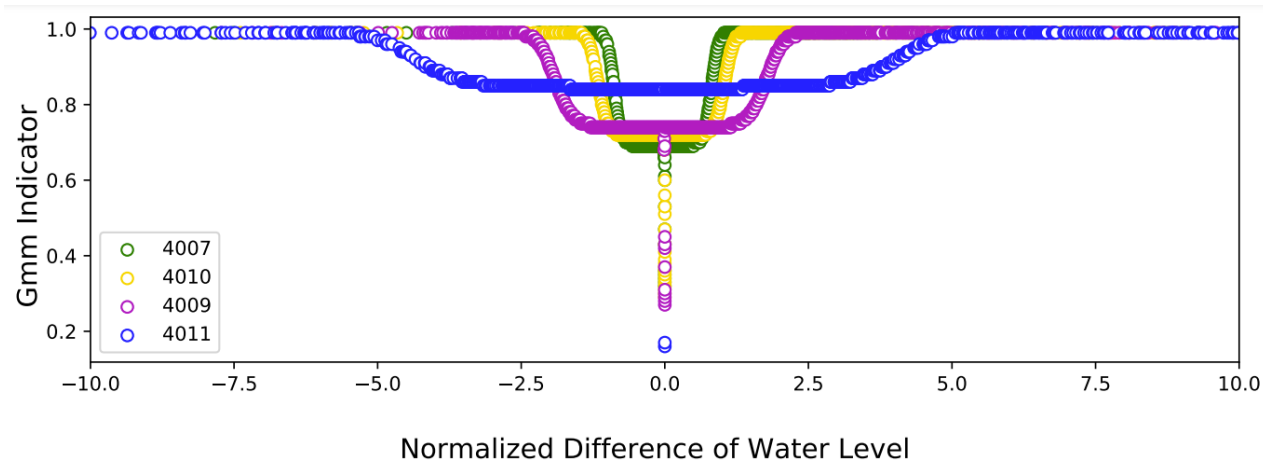


NEC is composed of three separate models, which can be trained in parallel:

- The **Normal** (N) model is trained to best fit normal values in the time series.
- The **Extreme** (E) model is trained to best fit extreme time series values.
- The **Classifier** (C) model is trained to detect when a certain value may be categorized as normal or extreme.

NEC is a purely single variate model; **NEC+** uses optional exogeneous other inputs.

GMM Indicator :



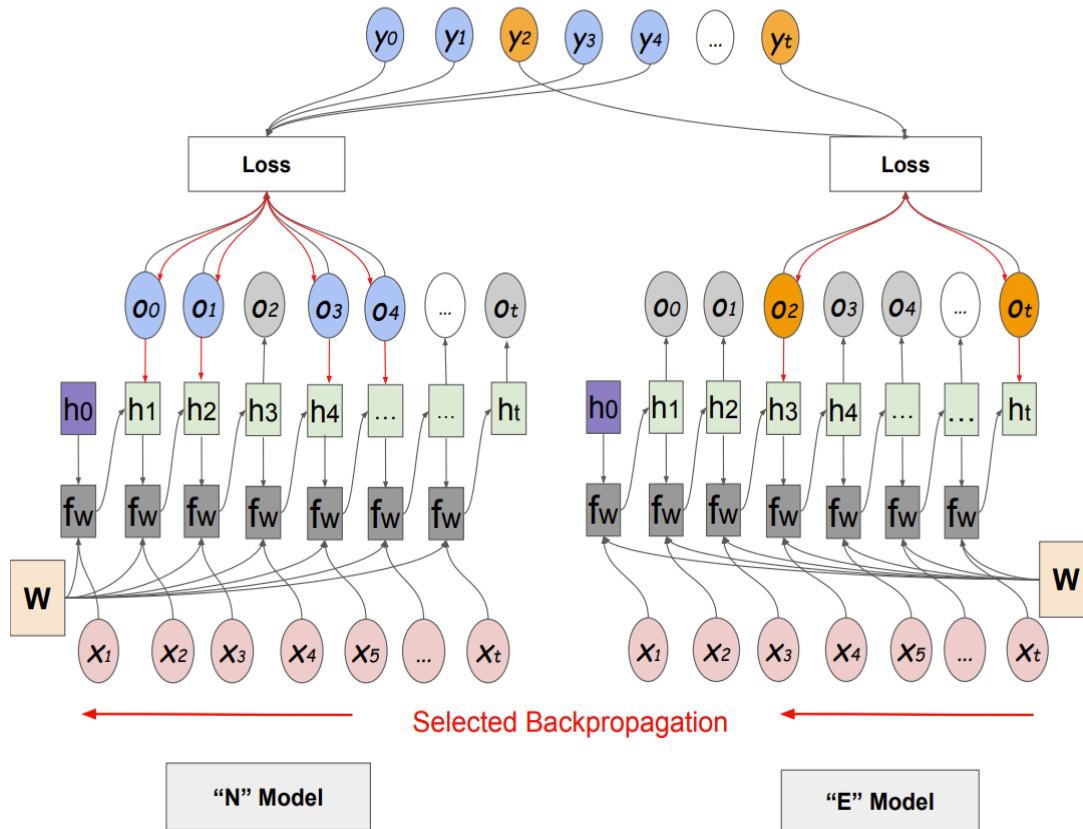
A Gaussian mixture model (GMM) is a weighted sum of M component Gaussian densities,

$$p(x|\lambda) = \sum_{i=1}^M w_i g(x|\mu_i, \Sigma_i),$$

where x is a D -dimensional continuous-valued vector, $w_i \forall i = 1, \dots, M$ are the mixture weights, and $g(x|\mu_i, \Sigma_i)$ are the component Gaussian densities.

We compute an indicator feature as the weighted sum of all component probabilities, given the weights learned when fitting the GMM model.

Selected Backpropagation :



Two-stage sampling policy:

- 1) randomly sample subsections of length $h + f$ from the series to use in training our models
- 2) perform stratified sampling of regions with and without extreme values, allowing the E and C models to oversample up to OS% samples with at least 1 extreme value in the prediction zone.

Selected Backpropagation:

N model: only normal values add to the loss;

E model: only extreme values add to the loss.

Parameterized Loss Function:

$$BCE(t, p) = -(t \times \log(p) + (1 - t) \times \log(1 - p))$$

$$L = \beta \times BCE(t, p^\alpha) + (1 - \beta) \times RMSE(t, p)$$

where α and β are parameters that can be tuned. Values $\alpha > 1$ cause the model to predict p values that are higher in general in order to minimize the distance between t and p^α .

Problem: for datasets with a high imbalance between the two classes, BCE will favor the prominent class.

- The BCE part: can be thought of as a blunt instrument that grossly exaggerates all misclassifications in order to more accurately predict the obscure class
- The RMSE part: allows for a more gentle penalty based on the distance between t and p .

Research Questions:

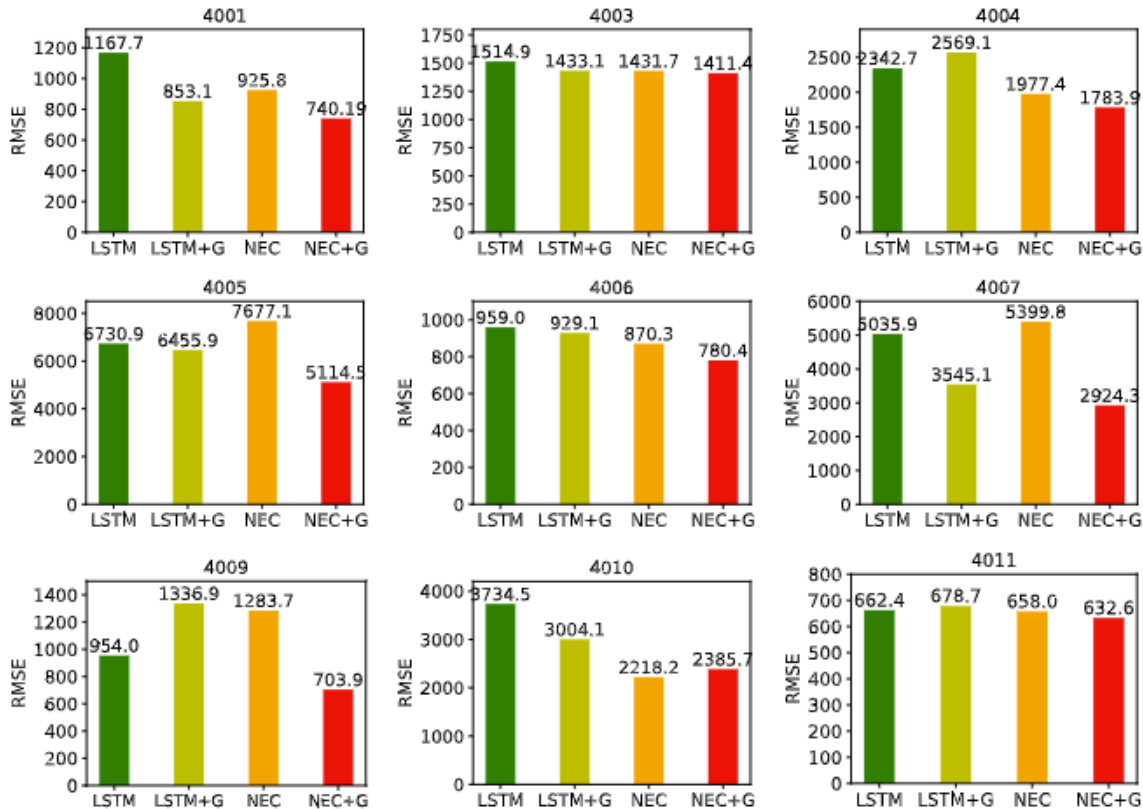
1. What is the effect of adding the GMM indicator to a model?
2. What is the effect of introducing exogenous features?
3. How do the loss function parameters affect performance?
4. How does NEC+ compare against state-of-the-art baselines?

Baselines:

- **ARIMA**
- **Facebook Prophet**
- **LSTM**
- **DNN-U**: univariate state-of-the-art LSTM-based encoder-decoder hydrologic model.
- **Attention-LSTM**: a state-of-the-art hydrologic model for stream-flow prediction.
- **N-BEATS**: a state-of-the-art time series prediction method that outperformed all competitors on the standard M3, M4 and TOURISM datasets.

Research Questions:

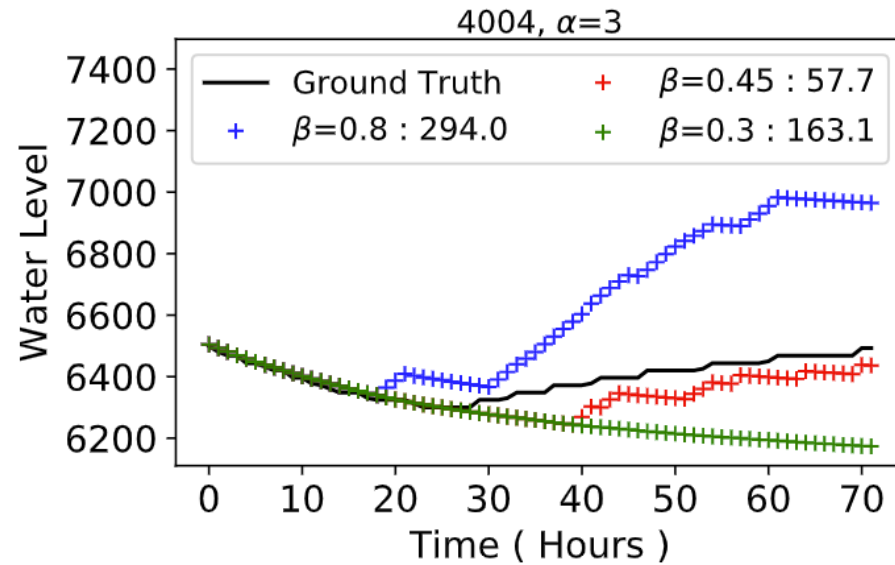
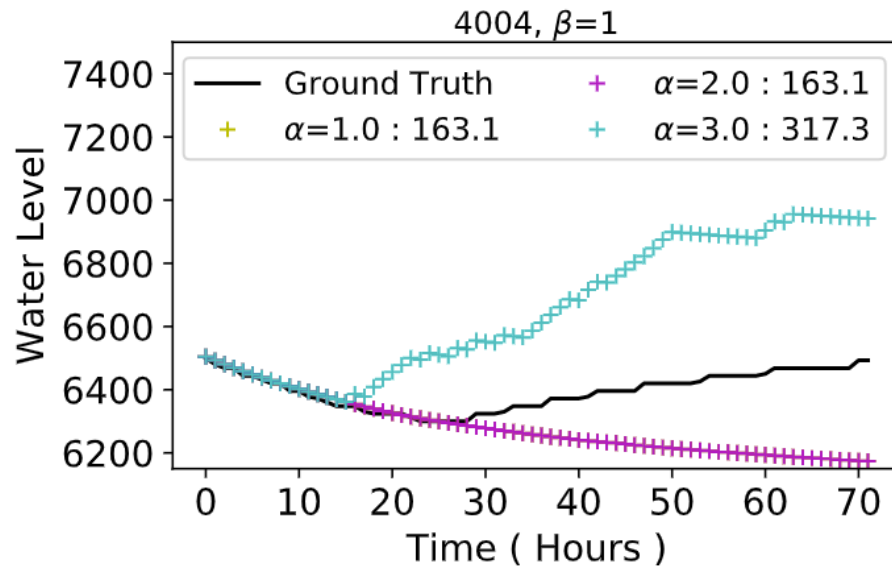
1. What is the effect of adding the GMM indicator to a model?
2. What is the effect of introducing exogenous features?



| Model/Reservoir | 4005 | 4007 | 4010 |
|-----------------|---------|---------|---------|
| LSTM | 6730.93 | 5035.91 | 3734.53 |
| LSTM+W | 7568.68 | 5728.30 | 4145.16 |
| LSTM+G | 6455.90 | 3545.19 | 3004.14 |
| LSTM+G+W | 9760.62 | 4128.37 | 2602.58 |
| NEC+G | 5114.49 | 2924.30 | 2385.77 |
| NEC+G+W (NEC+) | 4352.74 | 2092.73 | 2275.48 |

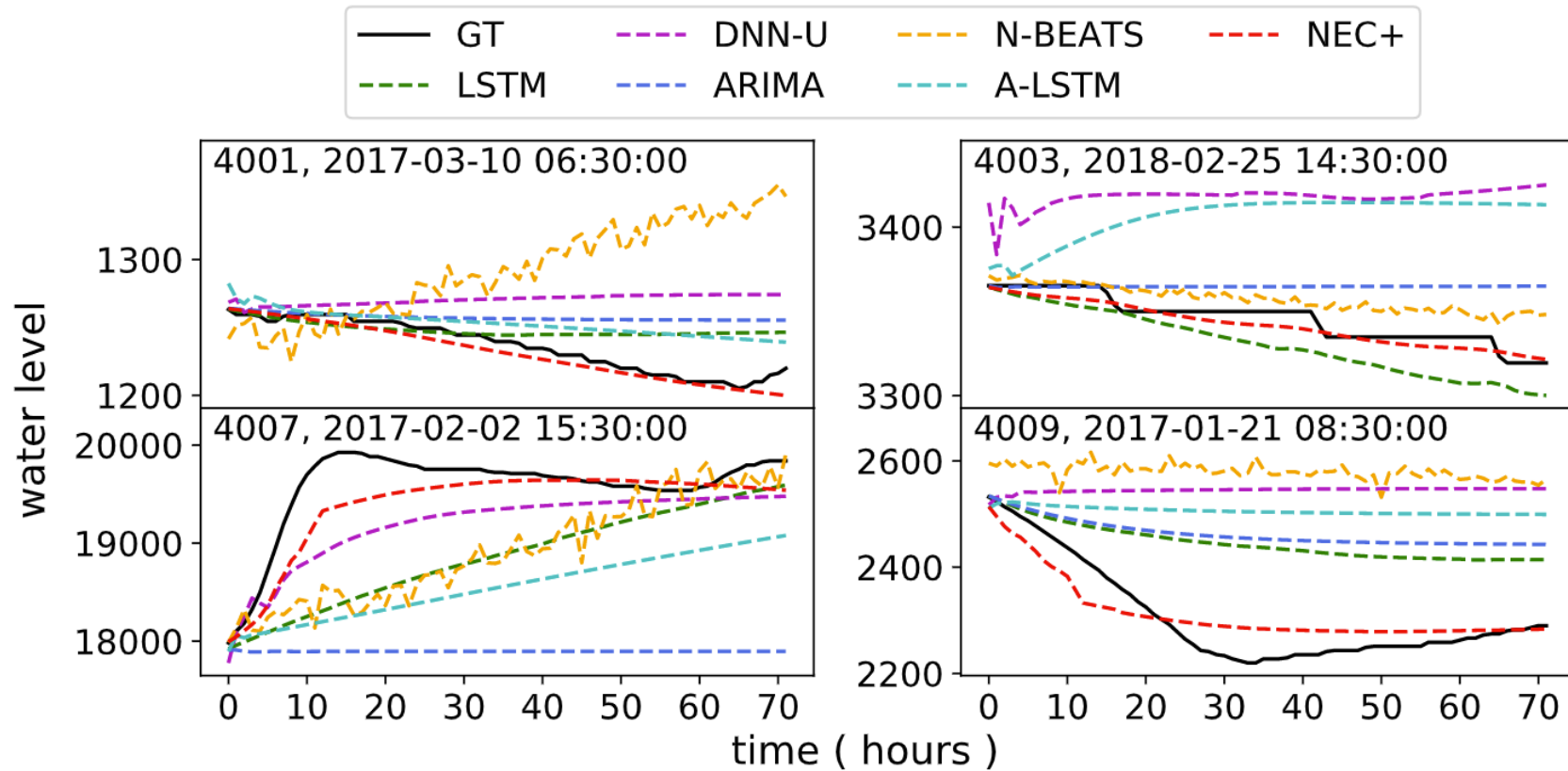
Research Questions:

3. How do the loss function parameters affect performance?



Research Questions:

4. How does NEC+ compare against state-of-the-art baselines?



Evaluation Overall:

Table 1: Effectiveness Comparison (RMSE) of NEC+ Against Baselines for 9 Reservoirs

| Model/Reservoir | 4001 | 4003 | 4004 | 4005 | 4006 | 4007 | 4009 | 4010 | 4011 |
|-----------------|---------------|----------------|----------------|----------------|---------------|----------------|---------------|----------------|---------------|
| ARIMA | 1016.32 | 1859.70 | 2501.97 | 9692.87 | 1039.38 | 5854.48 | 1060.05 | 3465.20 | 690.23 |
| Prophet | 8469.74 | 38827.22 | 95279.31 | 181607.50 | 20904.57 | 187603.80 | 28629.44 | 114115.4 | 2829.26 |
| LSTM | 1167.73 | 1514.90 | 2342.71 | 6730.93 | 959.05 | 5035.91 | 954.04 | 3734.53 | 662.48 |
| DNN-U | 1162.01 | 1597.72 | 3989.20 | 9878.41 | 983.27 | 4320.40 | 1411.63 | 4257.58 | 763.73 |
| A-LSTM | 878.71 | 1536.04 | 2548.56 | 8919.33 | 1638.65 | 13529.86 | 1064.15 | 2914.75 | 700.50 |
| N-BEATS | 937.24 | 1926.74 | 2280.83 | 7153.82 | 960.42 | 3153.76 | 1295.90 | 3162.17 | 514.30 |
| NEC+ | 740.19 | 1411.44 | 1783.92 | 4352.74 | 780.46 | 2092.73 | 703.93 | 2275.48 | 632.61 |

Table 3: MAPE of NEC+ vs. Baselines for 9 Reservoirs

| Model/Reservoir | 4001 | 4003 | 4004 | 4005 | 4006 | 4007 | 4009 | 4010 | 4011 |
|-----------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| ARIMA | 1.3573 | 0.7626 | 0.8694 | 1.2560 | 1.5401 | 0.8517 | 0.9504 | 1.7871 | 3.2914 |
| Prophet | 16.7877 | 19.8559 | 38.9642 | 35.6662 | 56.0537 | 32.9152 | 31.8069 | 45.2579 | 15.3312 |
| LSTM | 1.6697 | 0.6153 | 0.7450 | 1.0092 | 1.3264 | 0.9253 | 0.9298 | 2.5520 | 3.1282 |
| DNN-U | 1.6509 | 0.6812 | 1.8738 | 1.9394 | 1.4551 | 0.6509 | 1.5604 | 2.1582 | 3.7131 |
| A-LSTM | 1.3533 | 0.6506 | 0.8424 | 1.2060 | 2.8017 | 2.1738 | 0.9705 | 1.3986 | 3.4137 |
| N-BEATS | 1.3346 | 0.7972 | 0.7882 | 1.1405 | 2.0061 | 0.4709 | 1.4580 | 1.7146 | 2.3108 |
| NEC+ | 1.0319 | 0.5687 | 0.6030 | 0.6350 | 1.0662 | 0.3316 | 0.5992 | 1.2894 | 2.9237 |



Q & A

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